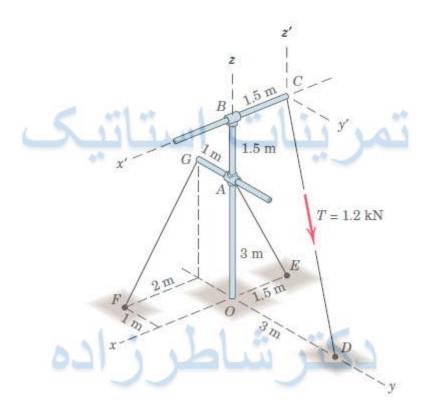


استاتیک

1

The rigid pole and cross-arm assembly is supported by the three cables shown. A turnbuckle at D is tightened until it induces a tension T in CD of 1.2 kN. Express T as a vector. Does it make any difference in the result which coordinate system is used?

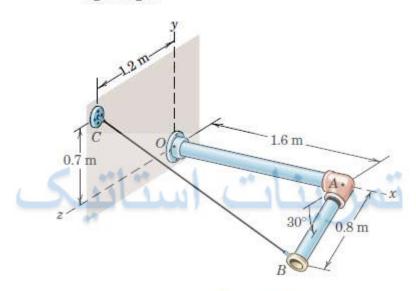




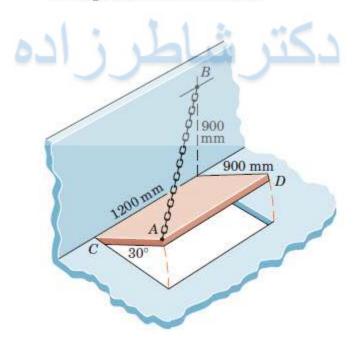
استاتیک

2

The cable BC carries a tension of 750 N. Write this tension as a force T acting on point B in terms of the unit vectors \mathbf{i} , \mathbf{j} , and \mathbf{k} . The elbow at A forms a right angle.



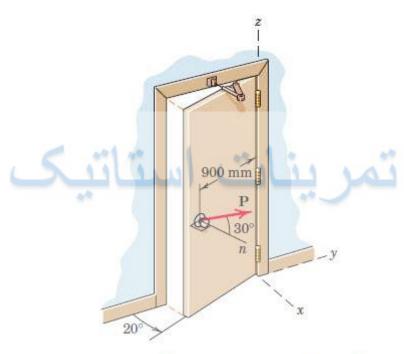
The access door is held in the 30° open position by the chain AB. If the tension in the chain is 100 N, determine the projection of the tension force onto the diagonal axis CD of the door.



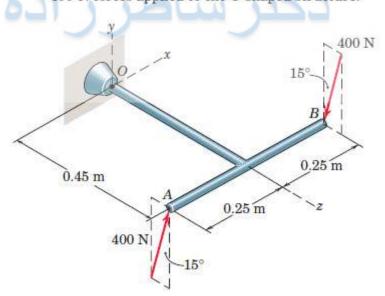


استاتیک

In opening a door which is equipped with a heavyduty return mechanism, a person exerts a force \mathbf{P} of magnitude 32 N as shown. Force \mathbf{P} and the normal n to the face of the door lie in a vertical plane. Compute the moment of \mathbf{P} about the z-axis.



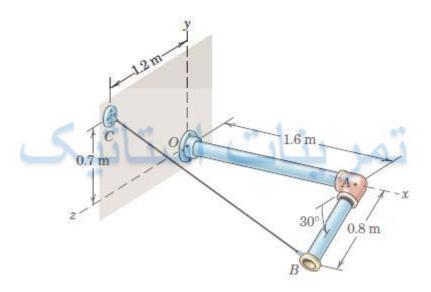
Determine the moment associated with the pair of 400-N forces applied to the T-shaped structure.





استاتیک

The right-angle pipe OAB of Prob. 2/108 is shown again here. Replace the 750-N tensile force which the cable exerts on point B by a force-couple system at point O.

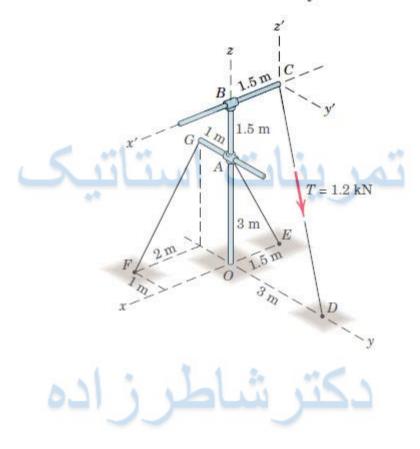


دكترشاطرزاده



استاتیک

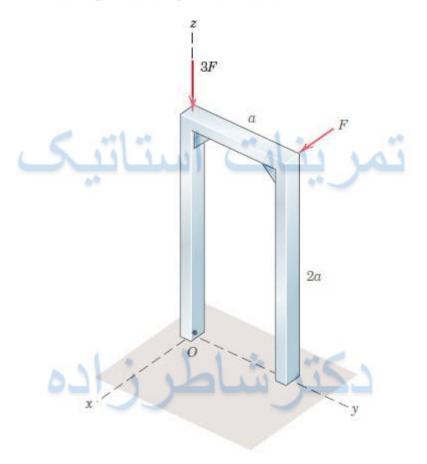
The rigid pole and cross-arm assembly of Prob. 2/105 is shown again here. Determine the vector expression for the moment of the 1.2-kN tension (a) about point O and (b) about the pole z-axis. Find each moment in two different ways.





استاتیک

Replace the two forces acting on the frame by a wrench. Write the moment associated with the wrench as a vector and specify the coordinates of the point P in the y-z plane through which the line of action of the wrench passes. Note that the force of magnitude F is parallel to the x-axis.





استاتیک

Replace the two forces acting on the pole by a wrench. Write the moment M associated with the wrench as a vector and specify the coordinates of the point P in the y-z plane through which the line of action of the wrench passes.

